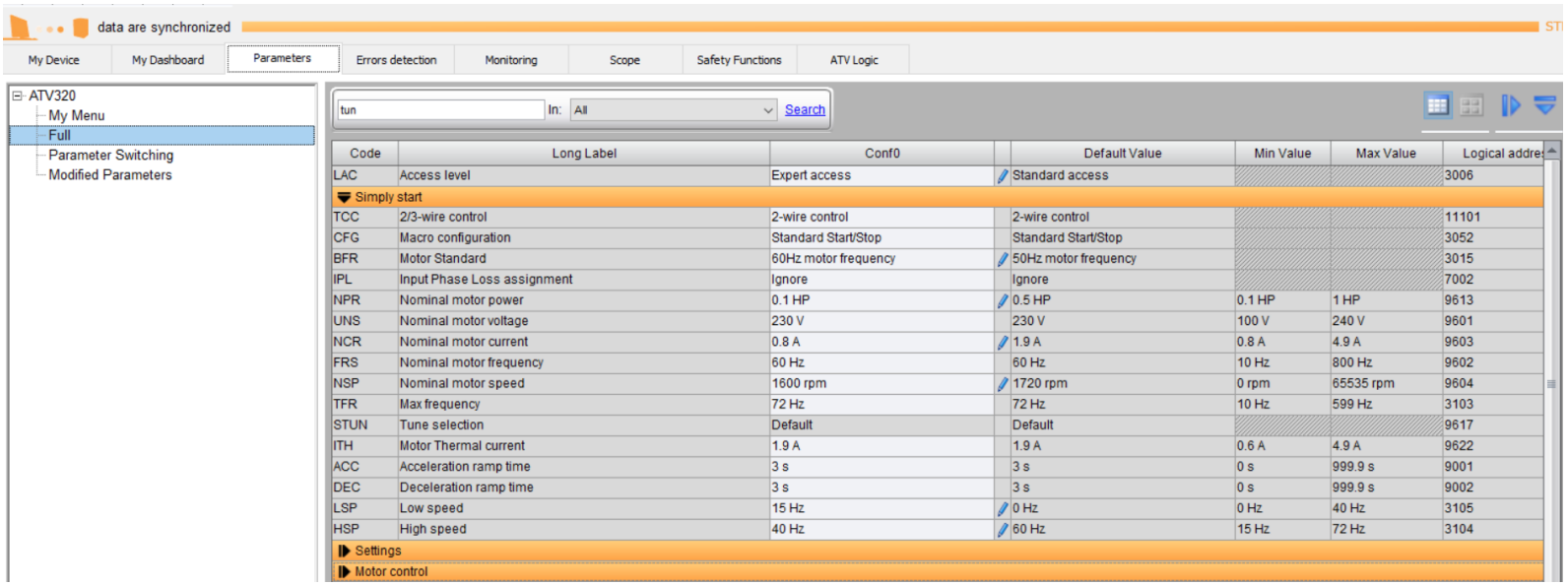
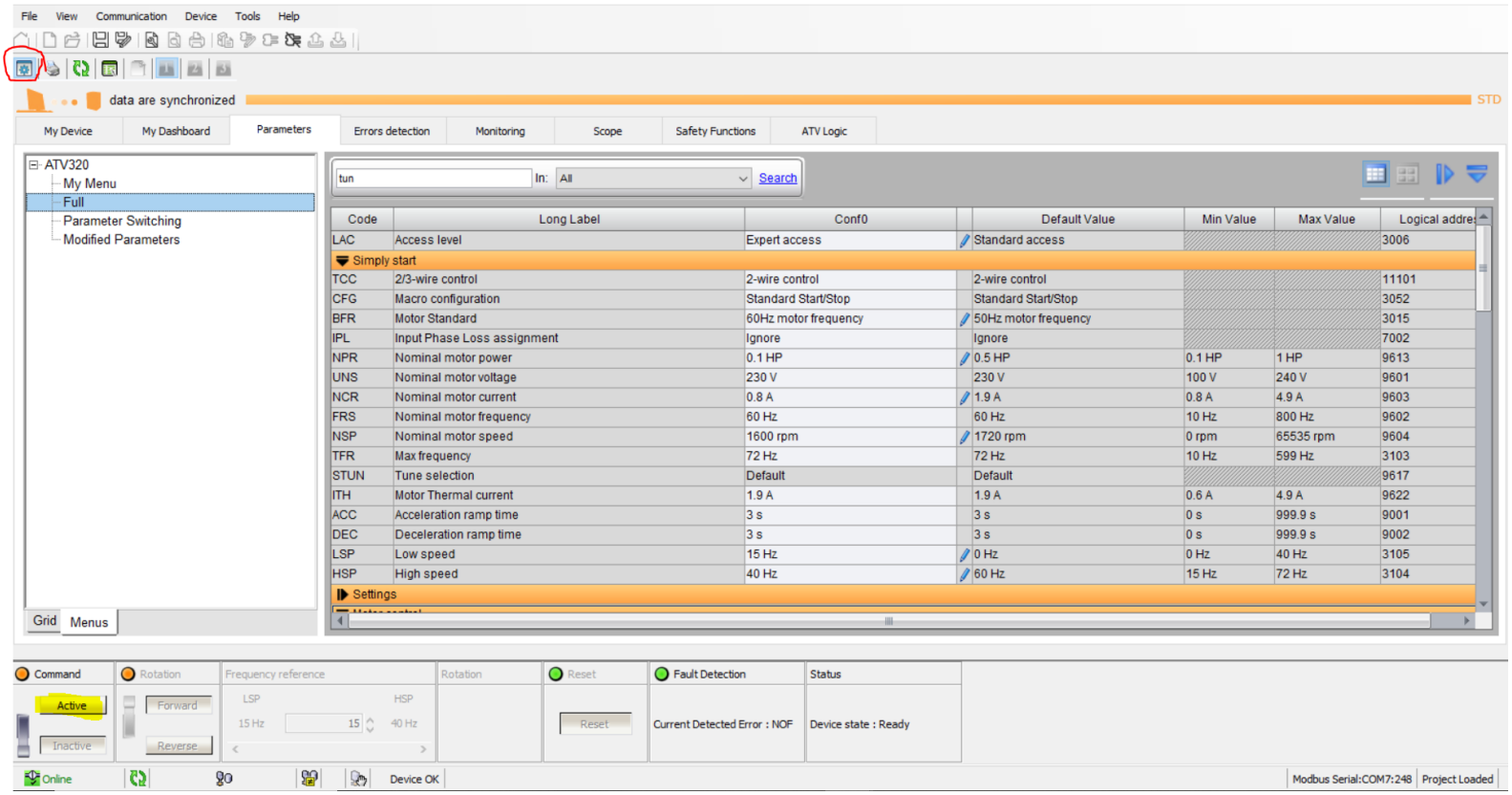
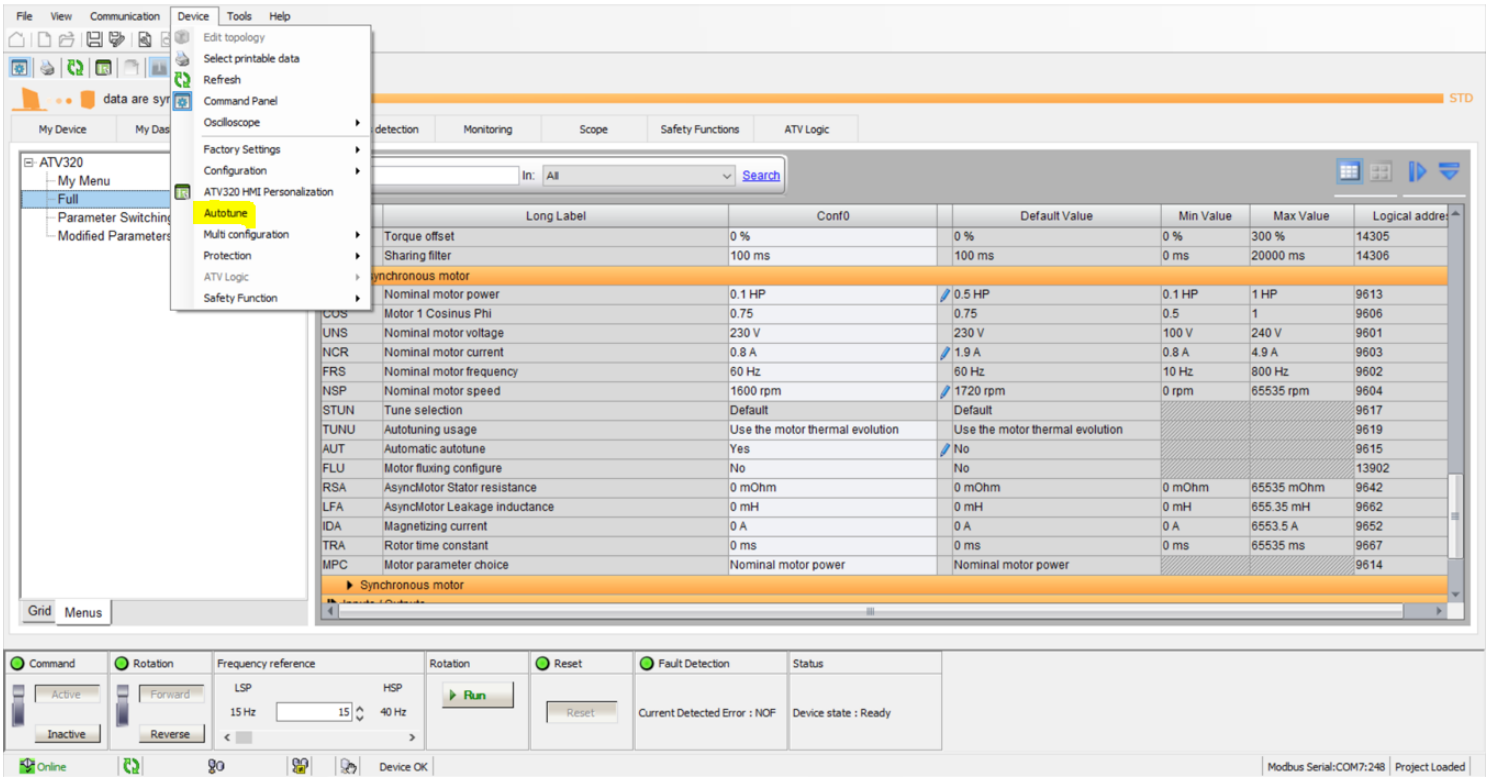
First fill the basic programming motor parameters of the motor; BFR, NPR, UNS, NCR, FRS, NSP. This is necessary so the drive can start the autotuning process and can have the correct feedback from the motor.



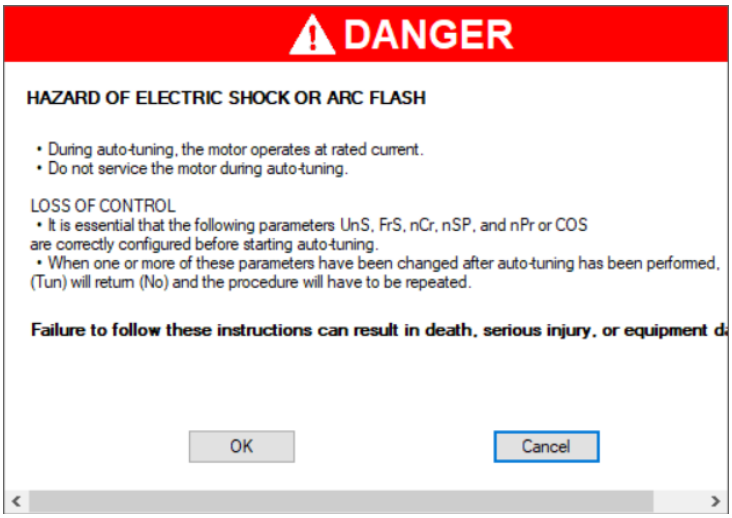
To perform the autotune it's necessary to activate the "Control Panel". You will click on the square with the gear and then click on "Activate" in the window that opens at the bottom.



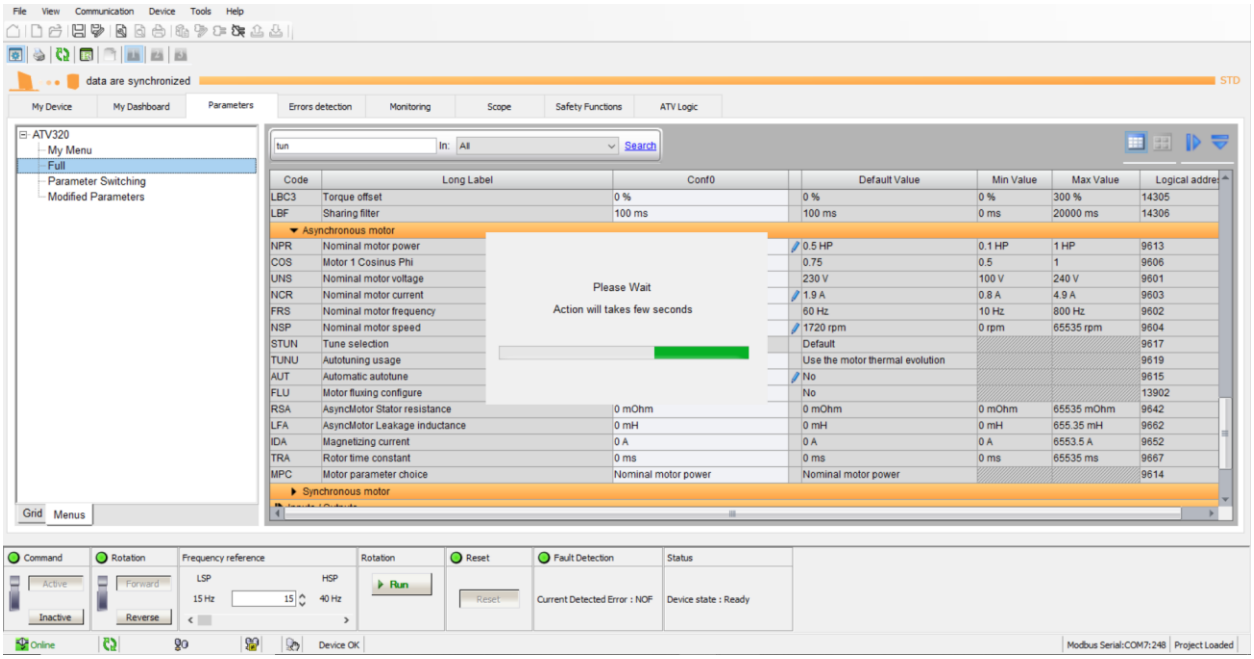
When the control panel command is active it will turn the circles from yellow to green. Then you can go to the “Device” menu and will select Autotune (highlighted), this option of Autotune is only available when the control panel command is active.



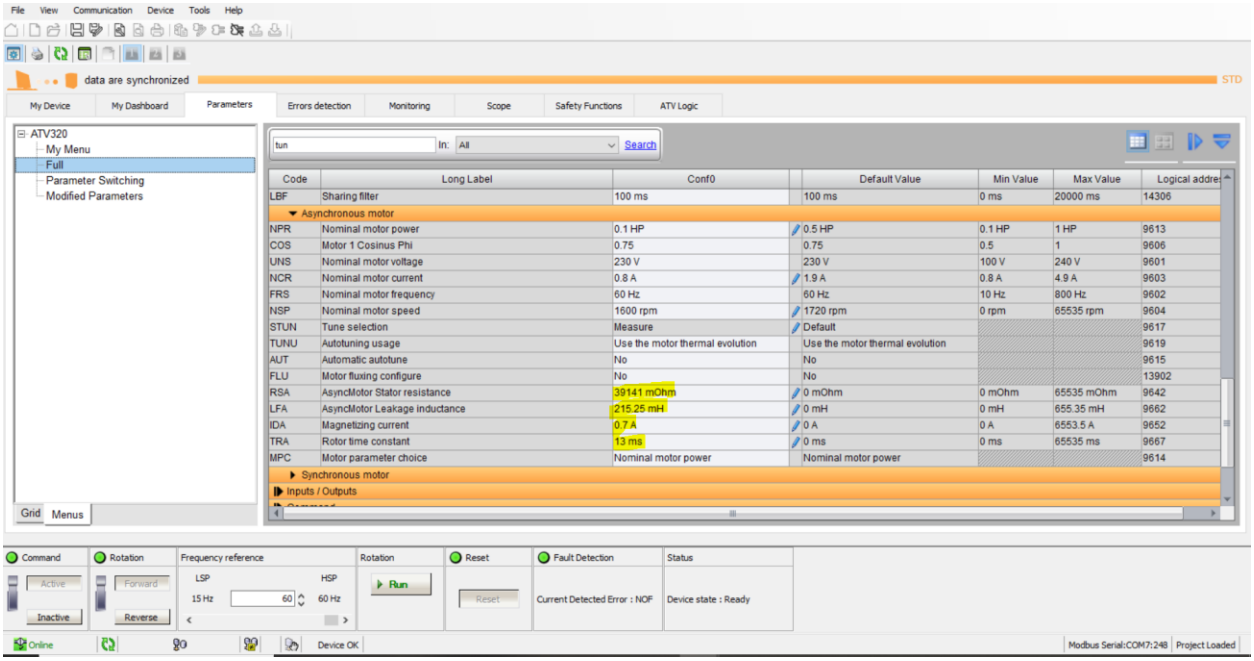
It will show the “DANGER” window that indicates that the motor will operate at rated current and the motor will rotate and will make some noise.



This autotune will take a couple of seconds.



After the autotune is complete, you can see that the parameters inside Motor control> Asynchronous motor (if it's an asynchronous motor) will be updated (e.g., RSA, LFA, IDA).



**This test was performed with a Schneider Demo and the motor was too small (0.03HP) and there were some complications with the process. With the correct size motor and with the correct setup of the basic motor parameters there should not be any issue.